# Lower Bounds for Graph Embeddings and Combinatorial Preconditioners 

Peter Richter<br>Joint work with Gary Miller to appear in SPAA 2004

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- Applications: packet routing, linear systems
- Upper bounds: $c(G, H), d(G, H) \leq O(n)$ and $\kappa_{f}(G, H) \leq O\left(n^{1+o(1)}\right)$ [Boman/Hendrickson]


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Main result:
- Condition number is largest when $G$ is a square mesh: $\kappa_{f}(G, H) \geq \Omega\left(n^{1-o(1)}\right)$


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- Conclusion


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The packet routing problem:

- Step 1: Path selection (fixed by embedding)
- Step 2: Motion schedule (model-dependent)
- Solvable in time $\Theta\left(c_{\varphi}(G, H)+d_{\varphi}(G, H)\right)$ in a particular store-and-forward model [Leighton/Maggs/Rao]


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M-matrices:
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- Arise in FDM/FEM for elliptic PDEs


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A generalized condition number:

- $\kappa_{f}(G, H)=\max _{x \perp j} \frac{x^{T} G x}{x^{T} H x} \cdot \max _{x \perp j} \frac{x^{T} H x}{x^{T} G x}=$ $\left(\max \lambda_{f}(G, H)\right) \cdot\left(\min \lambda_{f}(G, H)\right)^{-1}$


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- Rayleigh quotients compare power dissepation


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- Example: $H$ is a spanning tree of $G$


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Bounding the condition number from above:

- $\kappa_{f}(G, H) \leq O\left(\min _{\varphi} c_{\varphi}(G, H) \cdot d_{\varphi}(G, H)\right)$
[Gremban]


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- Congestion-times-dilation is strong, but false
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- For the simple square mesh, novel techniques are needed


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- Medium congestion, medium dilation, large condition number


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Two spanning trees for the planar square mesh:


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- Hybrid argument: $\kappa_{f}(G, H) \geq \Omega(n)$
- Is there a better spanning tree?


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- Bound $\kappa_{f}(G, H)$ by finding a particular shape


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- Either some tree is ill-shaped, or none are


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- Then $\kappa_{f}(G, H) \geq \Omega(p q)$
- Proof: Set potential $x$ at $e, \ldots, f$ to $0, \ldots, q$; then $\mathcal{E}_{G}(x) \geq \Omega\left(p q^{2}\right)$ and $\mathcal{E}_{H}(x) \leq O(q)$


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- Example: $p, q \geq \Omega(\sqrt{n}) \Rightarrow \kappa_{f}(G, H) \geq \Omega(n)$


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- Then $\kappa_{f}(G, H) \geq \Omega\left(t^{3} / r\right)$
- Proof: Choose a node $u$ at one end of $S^{\prime}$, and set potential $x$ at each $v \in E_{S^{\prime}}$ to $(u, v)$ distance; then $\mathcal{E}_{G}(x) \geq \Omega\left(t^{3}\right)$ and $\mathcal{E}_{H}(x) \leq O(r)$


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- Suppose subtree $S^{\prime \prime}$ has diameter $t$ and size $r$
- Then $\kappa_{f}(G, H) \geq \Omega\left(t^{3} / r\right)$
- Proof: Choose a node $u$ at one end of $S^{\prime}$, and set potential $x$ at each $v \in E_{S^{\prime}}$ to $(u, v)$ distance; then $\mathcal{E}_{G}(x) \geq \Omega\left(t^{3}\right)$ and $\mathcal{E}_{H}(x) \leq O(r)$
- Example:
$t \geq \Omega(\sqrt{n}), r \leq O(\sqrt{n}) \Rightarrow \kappa_{f}(G, H) \geq \Omega(n)$


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- Fix $\epsilon>0$, choose $s_{1}(\epsilon) \ll d=\Theta(\sqrt{n})$


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- Start with a subtree $S$ of mesh-diameter $d$, and perform a tree decomposition with parameter $s_{1}(\epsilon)$
- If no subtree is ill-shaped, apply Lemma A to conclude that $\kappa_{f}(G, H) \geq \Omega\left(n^{1-o(1)}\right)$


## Square Meshes

Proof of theorem (cont'd):

- If some subtree is ill-shaped, recurse; i.e., perform a tree decomposition on it with parameter $s_{2}(\epsilon)<s_{1}(\epsilon)$


## Square Meshes

Proof of theorem (cont'd):

- If some subtree is ill-shaped, recurse; i.e., perform a tree decomposition on it with parameter $s_{2}(\epsilon)<s_{1}(\epsilon)$
- Repeat as necessary until some subtree is extremely ill-shaped, then apply Lemma B to conclude that $\kappa_{f}(G, H) \geq \Omega\left(n^{1-o(1)}\right)$


## Conclusion

Extension to spanning subgraphs:

- Let $H$ have Euler characteristic $k$


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- Let $H$ have Euler characteristic $k$
- Partition $H$ into "vines"
- Lower bounds hold with $n$ replaced by $\frac{n}{k+1}$
- Upper bounds hold similarly [Spielman/Teng]


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- Is $\kappa_{f}(G, H)=\Theta(n)$ optimal for the square mesh?


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- Is $\kappa_{f}(G, H)=\Theta(n)$ optimal for the square mesh?
- Is there a single spanning tree optimizing congestion, dilation, and condition number simultaneously?
- Can we find the optimal spanning tree efficiently?

