Lower Bounds for Graph Embeddings and Combinatorial Preconditioners

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Joint work with Gary Miller to appear in SPAA 2004

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- Minimize the congestion c(G, H), dilation d(G, H), or condition number $\kappa_f(G, H)$
- Applications: packet routing, linear systems
- Upper bounds: $c(G, H), d(G, H) \leq O(n)$ and $\kappa_f(G, H) \leq O(n^{1+o(1)})$ [Boman/Hendrickson]

Folklore results:

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Main result:

• Condition number is largest when G is a square mesh: $\kappa_f(G, H) \ge \Omega(n^{1-o(1)})$

*This talk:*Introduction

- Introduction
- Embeddings and preconditioners

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- Expanders and cycles

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A graph embedding $\varphi : G \hookrightarrow H$... • Maps nodes in *G* to nodes in *H*

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The routing view of an embedding:G is guest (demands), *H* is host (links)

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 The packet routing problem:
- Step 1: Path selection (fixed by embedding)
- Step 2: Motion schedule (model-dependent)
- Solvable in time $\Theta(c_{\varphi}(G, H) + d_{\varphi}(G, H))$ in a particular store-and-forward model [Leighton/Maggs/Rao]

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- Arise in FDM/FEM for elliptic PDEs

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A generalized condition number:

• $\kappa_f(G, H) = \max_{x \perp j} \frac{x^T G x}{x^T H x} \cdot \max_{x \perp j} \frac{x^T H x}{x^T G x} = (\max \lambda_f(G, H)) \cdot (\min \lambda_f(G, H))^{-1}$

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 Rayleigh quotients compare power dissepation
The classical conjugate gradient method:

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- Example: H is a spanning tree of G

Bounding the condition number from above: • $\kappa_f(G, H) \leq O(\min_{\varphi} c_{\varphi}(G, H) \cdot d_{\varphi}(G, H))$ [Gremban]

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- Congestion-plus-dilation is easy, but weak
- For the simple square mesh, novel techniques are needed

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Two spanning trees for the planar square mesh:



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Upper bounds for the planar square mesh:

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- Hence, $\kappa_f(G, H) \leq O(n)$

Lower bounds for particular spanning trees:

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- Hybrid argument: $\kappa_f(G, H) \ge \Omega(n)$
- Is there a better spanning tree?

Main result:

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- If G is a square mesh and H is a spanning tree, then $\kappa_f(G, H) \ge \Omega(n^{1-o(1)})$
- Proof idea:
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- Bound $\kappa_f(G, H)$ by finding a particular shape

A tree decomposition:

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- Either some tree is ill-shaped, or none are

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- Example: $p, q \ge \Omega(\sqrt{n}) \Rightarrow \kappa_f(G, H) \ge \Omega(n)$

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• Proof: Choose a node u at one end of S', and set potential x at each $v \in E_{S'}$ to (u, v)distance; then $\mathcal{E}_G(x) \ge \Omega(t^3)$ and $\mathcal{E}_H(x) \le O(r)$

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• Example: $t \ge \Omega(\sqrt{n}), r \le O(\sqrt{n}) \Rightarrow \kappa_f(G, H) \ge \Omega(n)$

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Proof of theorem:

- Fix $\epsilon > 0$, choose $s_1(\epsilon) << d = \Theta(\sqrt{n})$
- Start with a subtree *S* of mesh-diameter *d*, and perform a tree decomposition with parameter $s_1(\epsilon)$
- If no subtree is ill-shaped, apply Lemma A to conclude that $\kappa_f(G, H) \ge \Omega(n^{1-o(1)})$

Proof of theorem (cont'd):

• If some subtree is ill-shaped, recurse; i.e., perform a tree decomposition on it with parameter $s_2(\epsilon) < s_1(\epsilon)$

Proof of theorem (cont'd):

- If some subtree is ill-shaped, recurse; i.e., perform a tree decomposition on it with parameter $s_2(\epsilon) < s_1(\epsilon)$
- Repeat as necessary until some subtree is extremely ill-shaped, then apply Lemma B to conclude that $\kappa_f(G, H) \ge \Omega(n^{1-o(1)})$

*Extension to spanning subgraphs:*Let *H* have Euler characteristic *k*

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- Upper bounds hold similarly [Spielman/Teng]

Open questions:

• Is $\kappa_f(G, H) = \Theta(n)$ optimal for the square mesh?
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- Is there a single spanning tree optimizing congestion, dilation, and condition number simultaneously?
- Can we find the optimal spanning tree efficiently?