

# Spanners with Slack

Michael Dinitz

Joint work with Hubert Chan and Anupam Gupta

Computer Science Department  
Carnegie Mellon University

Workshop on Flexible Network Design  
Bertinoro  
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# Outline

- 1 Introduction
  - Spanners
  - Slack
- 2 Slack Spanners
  - Main Result
  - Gracefully Degrading Spanners
- 3 Applications etc.
  - Distance Oracles
  - Distance Labelings
  - Other slack spanner results
- 4 Conclusion

# Spanner Definition

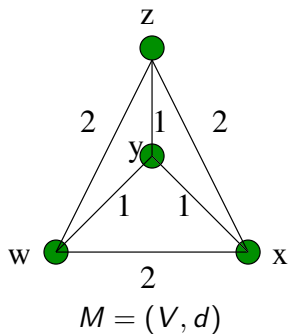
- Main problem: small representation of metric space

## Definition

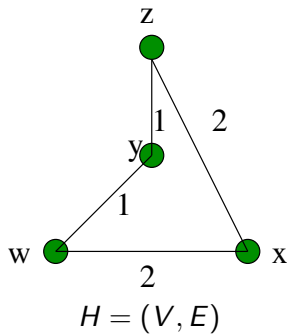
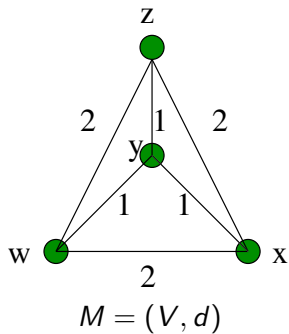
Give a metric  $(V, d)$ , a  $t$ -spanner  $H = (V, E)$  is a weighted graph such that for all  $u, v \in V$ ,  $d(u, v) \leq d_H(u, v) \leq t \cdot d(u, v)$

- $t$  is the *stretch* or the *distortion*
- $|E|$  measures how sparse or small the spanner is. *Really* want  $|E| = O(n)$
- Want to minimize  $|E|$  and  $t$ , i.e. create a low-stretch sparse spanner

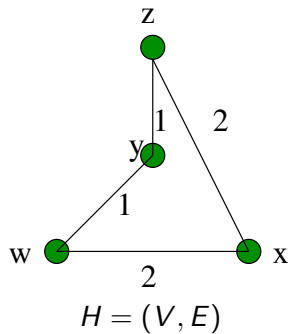
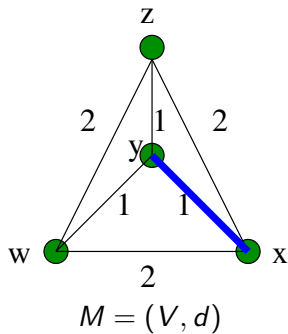
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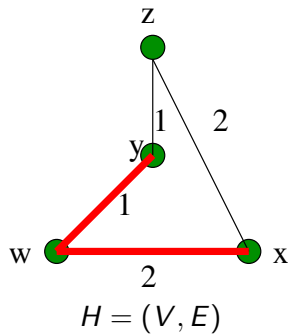
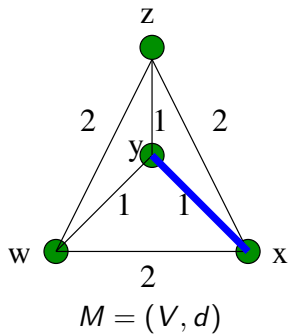
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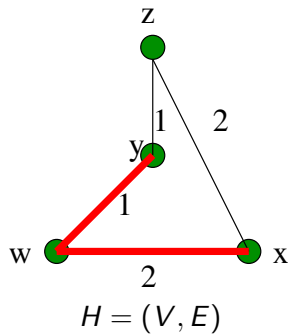
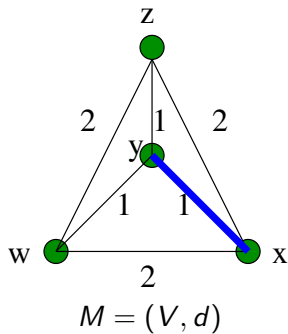
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$$\text{Stretch} = d_H(x, y) / d(x, y) = 3 / 1 = 3$$



# Research on Spanners

- Classic research:
  - Awerbuch '85: Inspired study of spanners
  - Peleg & Schaffer '89
  - Althofer, Das, Dobkin, Joseph, & Soares: Sparse spanners for weighted graphs
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  - Euclidean spanners
- New research
  - Baswana et al: Sparse *additive* spanners
  - Lower bounds for additive and Euclidean spanners

# Simple Algorithm

## Theorem (Althofer et al.)

*For any integer  $k$ , a  $(2k - 1)$ -spanner with  $O(n^{1+1/k})$  edges can be constructed efficiently*

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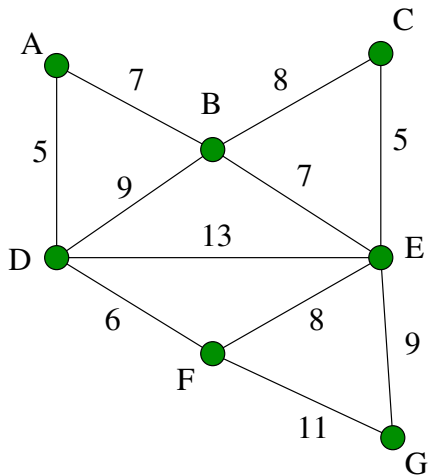
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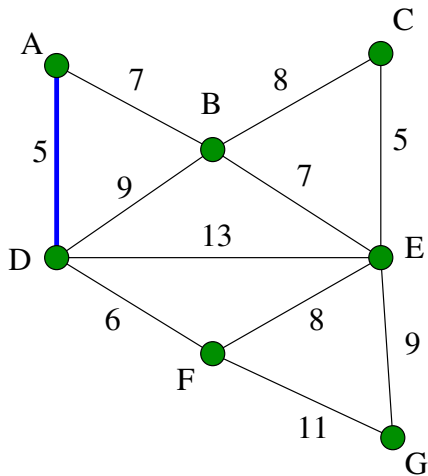
Use a Kruskal-like algorithm:

- Initialize  $H$  to be the empty graph
- Let  $\{u, v\}$  be shortest edge we haven't looked at yet
- If  $d_H(u, v) > (2k - 1)d(u, v)$ , put  $\{u, v\}$  in  $H$
- Otherwise discard  $\{u, v\}$  and repeat

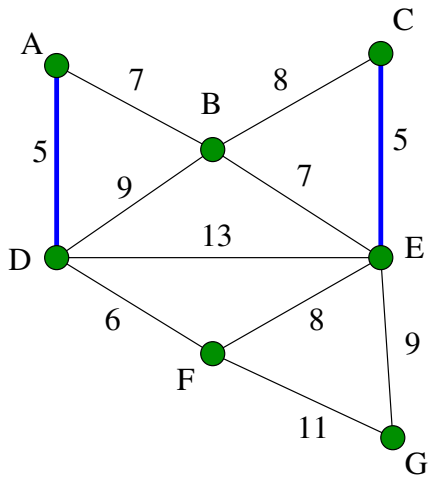
# Althofer Example ( $k = 2$ )



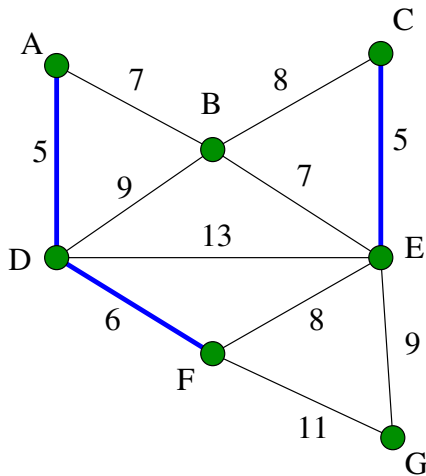
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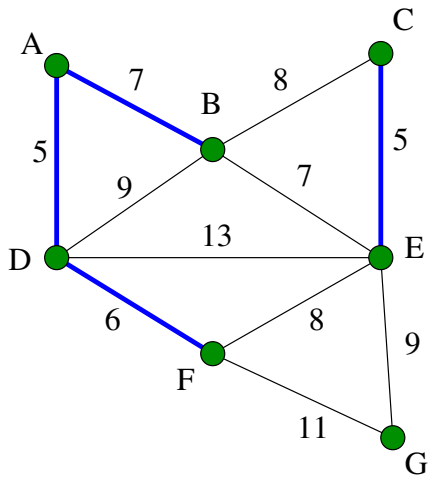


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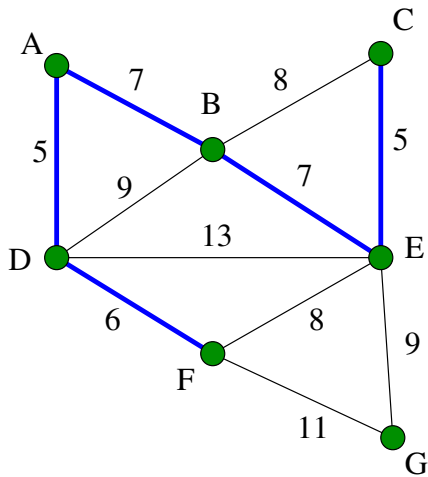




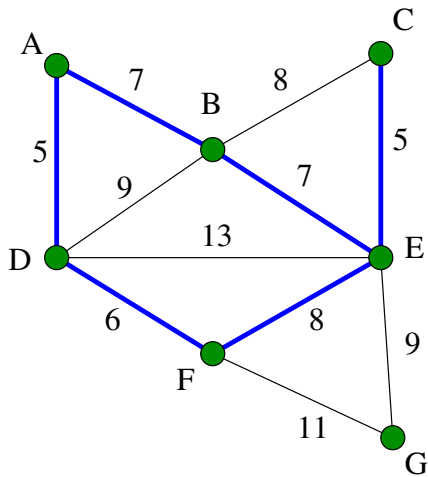
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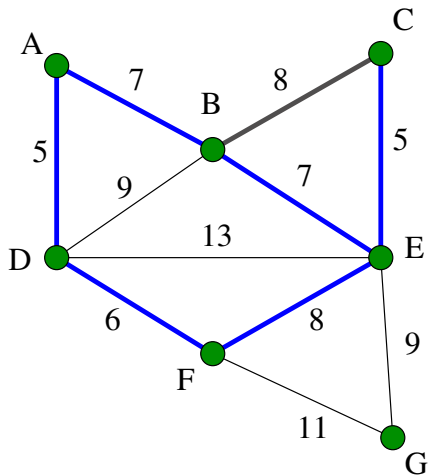
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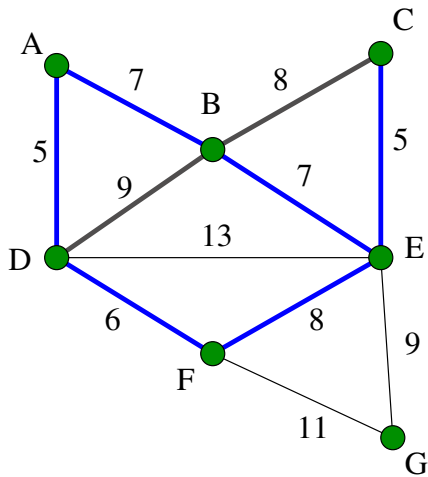
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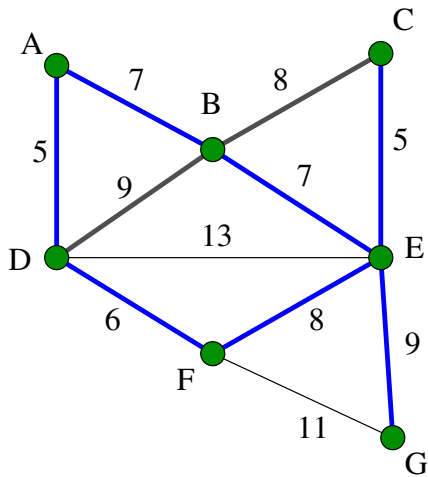


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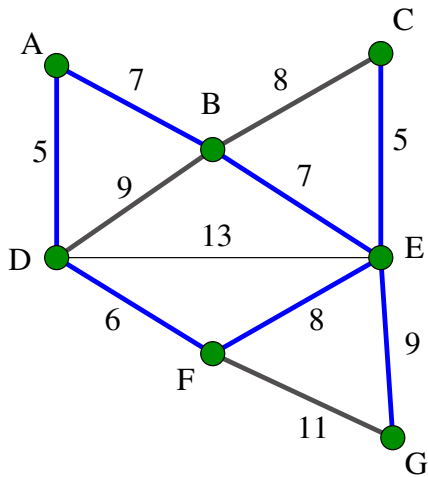


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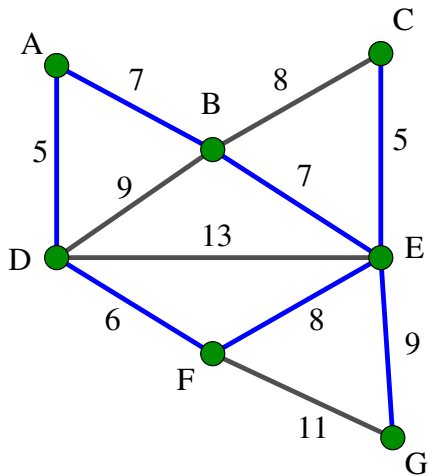


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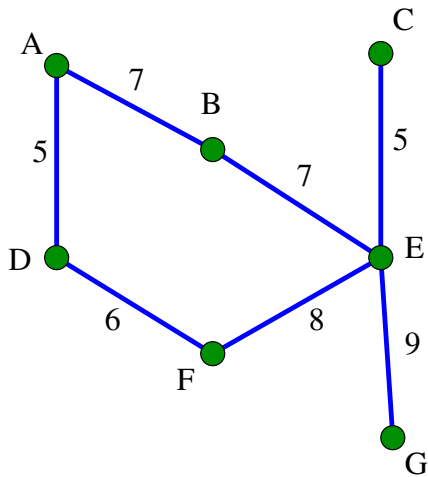


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- Stretch: by construction.
- Sparse:
  - Suppose edge  $e = \{u, v\}$  creates a cycle  $C$
  - Every other edge on  $C$  shorter than  $e$
  - Without  $e$ , the distance between  $u$  and  $v$  was more than  $(2k - 1)\text{length}(e)$
  - So at least  $2k - 1$  other edges on  $C$
  - Girth at least  $2k - 1$
- Well-known graph theory theorem: Girth of  $2k - 1$  implies  $|E| = O(n^{1+1/k})$

# Althofer is optimal

- Erdos girth conjecture: For every  $k$ , there is a graph with  $\Omega(n^{1+1/k})$  edges and girth  $2k - 1$
- Implies that the Althofer spanner is tight (well, at least for subgraph spanners...)
- So if we want  $O(n)$  edges, we need stretch of  $\Omega(\log n)$ !

# What Now?

- In practice:
  - ①  $\log n$  stretch is too large
  - ② Don't need low stretch for *all* pairs
- Use 2 to fix 1
- How well can we do? Ignore 5% of pairs and get  $O(\sqrt{\log n})$  stretch on the rest?  $O(\log \log n)$ ?  $O(1)$ ?

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- Ignoring a constant fraction of pairs lets us prove constant distortion on the rest!

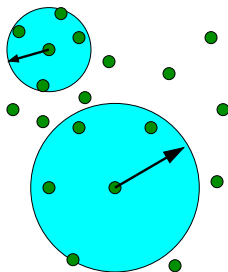
# $\epsilon$ -Neighborhoods

- Basic idea: ignoring small distances helps with large distances

## Definition

Given  $\epsilon$ , for any point  $v \in V$ , the  $\epsilon$ -neighborhood  $N_\epsilon(v)$  consists of the closest  $\epsilon n$  points to  $v$

- $R(v, \epsilon) = \min\{r : |B(v, r)| \geq \epsilon n\}$
- $v$  is  $\epsilon$ -far from  $u$  if  $d(u, v) \geq R(u, \epsilon)$





# Slack definitions

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- KSW '04, ABCDGKNS '05, ABN '06

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Given a metric  $(V, d)$ , a  $t$ -spanner  $H = (V, E)$  has  $\epsilon$ -slack if  $d(u, v) \leq d_H(u, v) \leq t \cdot d(u, v)$  for all but  $\epsilon n^2$  pairs  $\{u, v\}$

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- More restrictive definition:

## Definition (Uniform Slack)

Given a metric  $(V, d)$ , a  $t$ -spanner  $H = (V, E)$  has  $\epsilon$ -uniform slack if for all  $u, v \in V$  such that  $v$  is  $\epsilon$ -far from  $u$ ,  $d(u, v) \leq d_H(u, v) \leq t \cdot d(u, v)$

# Conversion Theorem

## Theorem

*Suppose there exists an algorithm to construct a  $t(n)$ -stretch spanner with  $h(n)$  edges for any metric. Then we can find an  $\epsilon$ -slack spanner with  $5 + 6t(\frac{1}{\epsilon})$  stretch and  $n + h(\frac{1}{\epsilon})$  edges.*

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We can apply this to the Althofer spanner:

## Corollary

*For any metric, for any  $0 < \epsilon < 1$ , for any integer  $k > 0$ , there exists a  $(12k - 1)$ -spanner with  $\epsilon$ -slack of size  $n + O((\frac{1}{\epsilon})^{1+1/k})$*

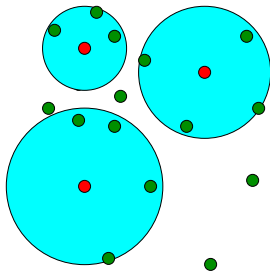
# Density Net

- Intuition: Small set of points that approximates the metric
- Recall that  $R(u, \epsilon) = \min\{r : |B(u, r)| \geq \epsilon n\}$

## Definition

An  $\epsilon$ -density net is a subset  $N$  of  $V$  such that

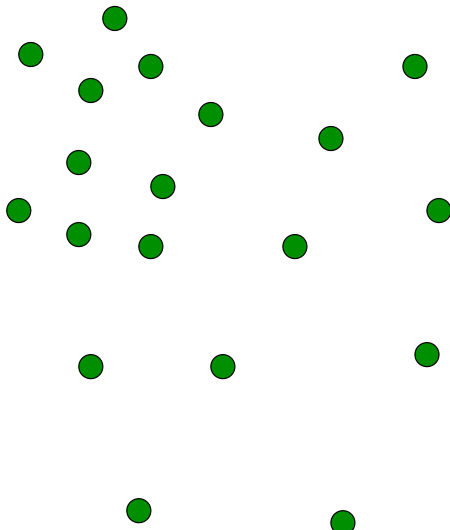
- 1 For all  $x \in V$ , there is some  $y \in N$  s.t.  $d(x, y) \leq 2R(x, \epsilon)$
- 2  $|N| \leq \frac{1}{\epsilon}$



# Constructing a Density Net

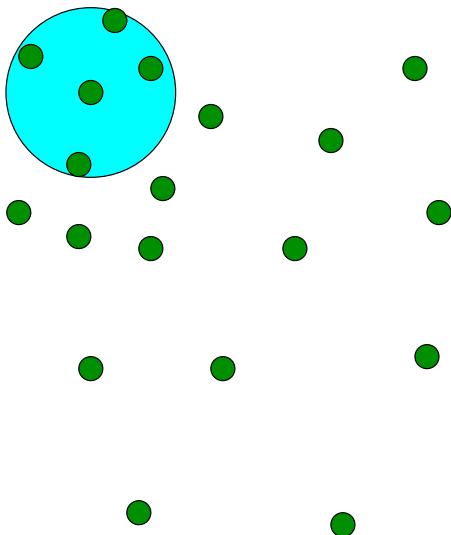
- ① Put points in a list  $L$  by non-decreasing value of  $R(\cdot, \epsilon)$
- ② Initialize  $N := \emptyset$ .
- ③ While  $L$  is non-empty:
  - ① Remove first point  $v$  from  $L$
  - ② If there exists  $u \in N$  s.t.  $N_\epsilon(v)$  and  $N_\epsilon(u)$  intersect, then discard  $v$ ; otherwise add  $v$  to  $N$

# Density Net Example

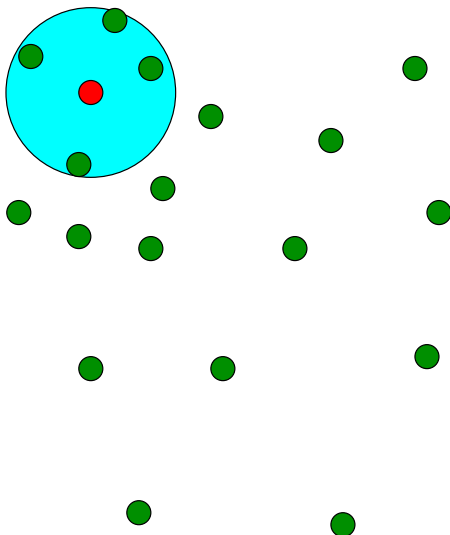




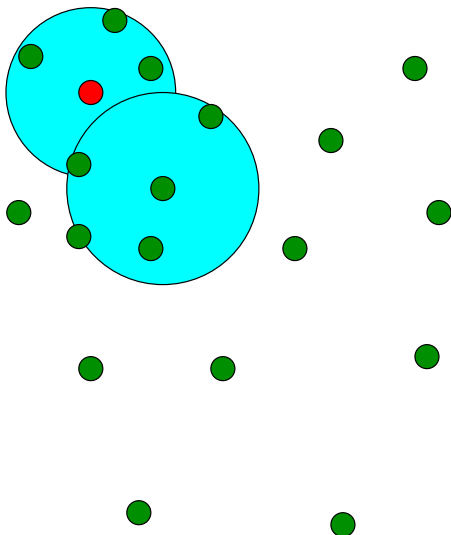
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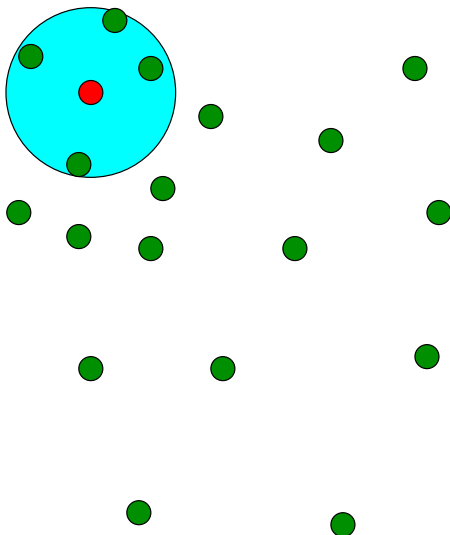
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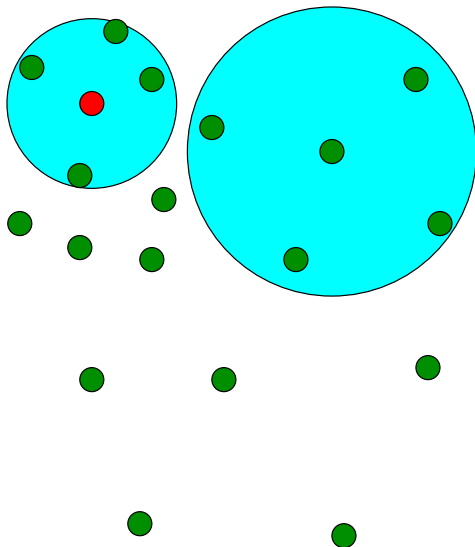
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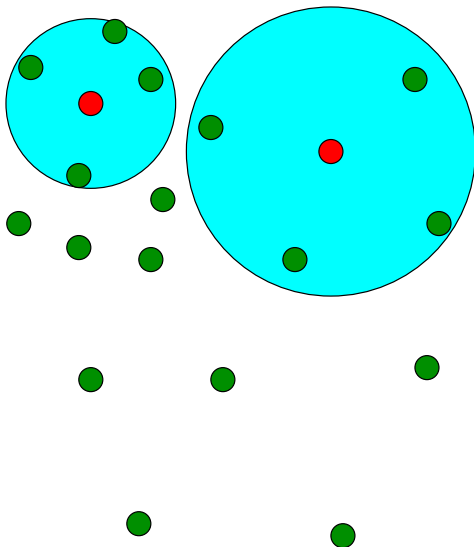
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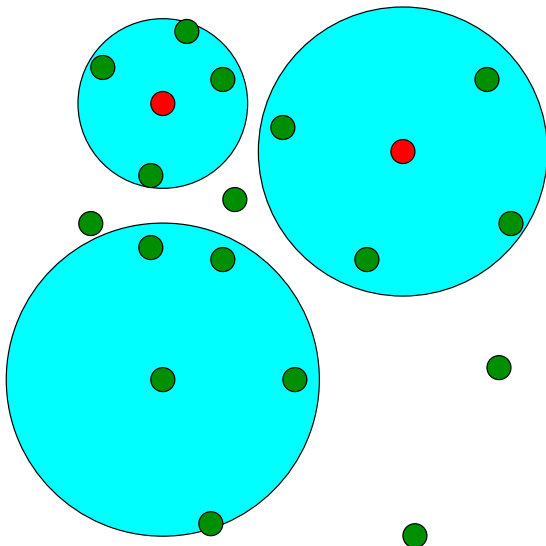
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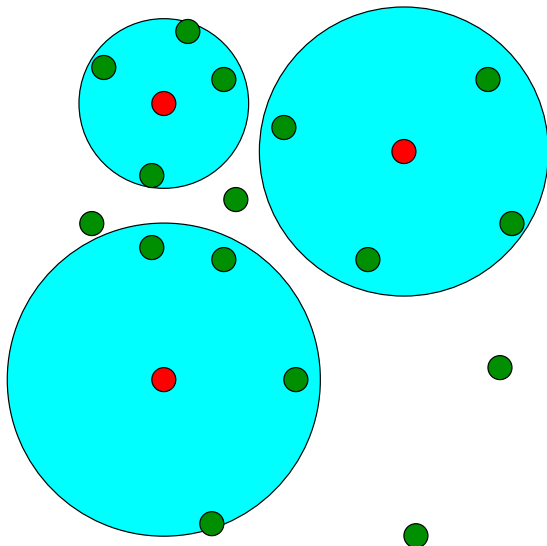
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  - 1 For all  $x \in V$  there is some  $y \in N$  such that  $d(x, y) \leq 2R(x, \epsilon)$
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  - ②  $|N| \leq \frac{1}{\epsilon}$
- Net property:
  - If  $x \in N$  then we're good.
  - Else there is  $y \in N$  before  $x$  s.t.  $N_\epsilon(x)$  and  $N_\epsilon(y)$  intersect. So  $d(x, y) \leq R(x, \epsilon) + R(y, \epsilon) \leq 2R(x, \epsilon)$

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- Size property:
  - For different  $u, v \in N$ ,  $N_\epsilon(u)$  and  $N_\epsilon(v)$  are disjoint
  - Each  $|N_\epsilon(u)| \geq \epsilon n$ , so  $|N| \leq \frac{1}{\epsilon}$

# Conversion Algorithm

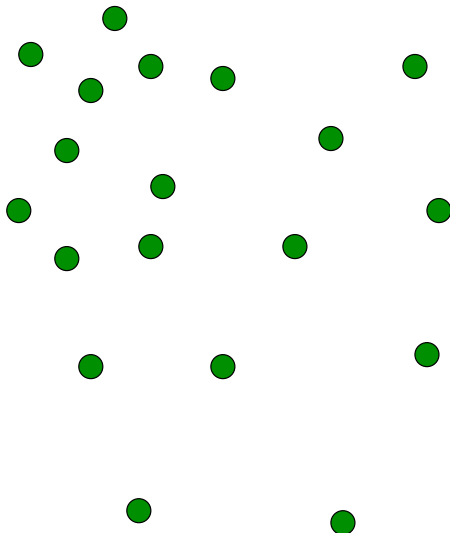
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- 3 For all  $u \in V \setminus N$ , add an edge to the nearest point in  $N$

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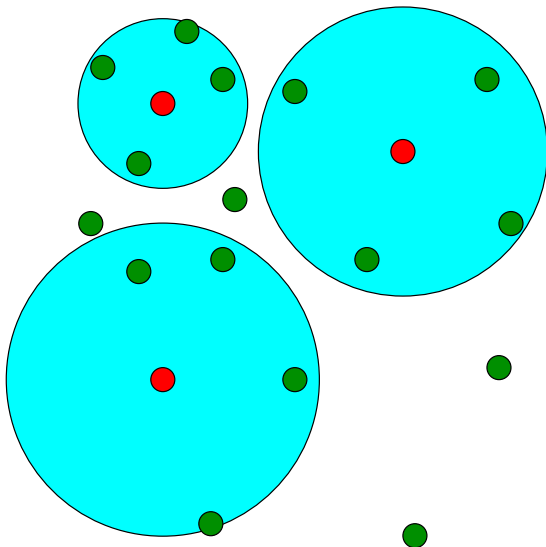
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Obviously sparse:  $O(n + h(\frac{1}{\epsilon}))$  edges

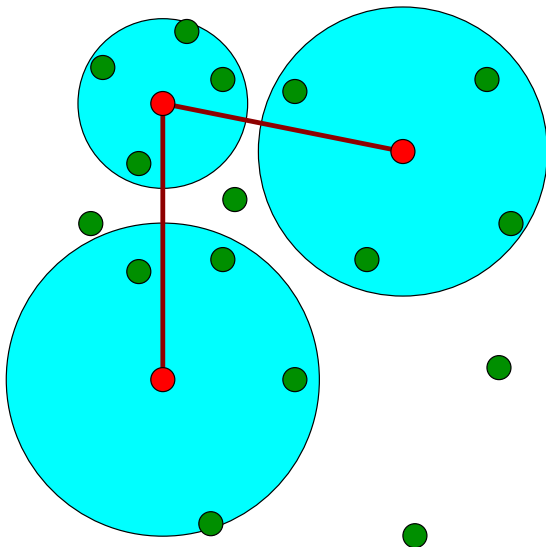
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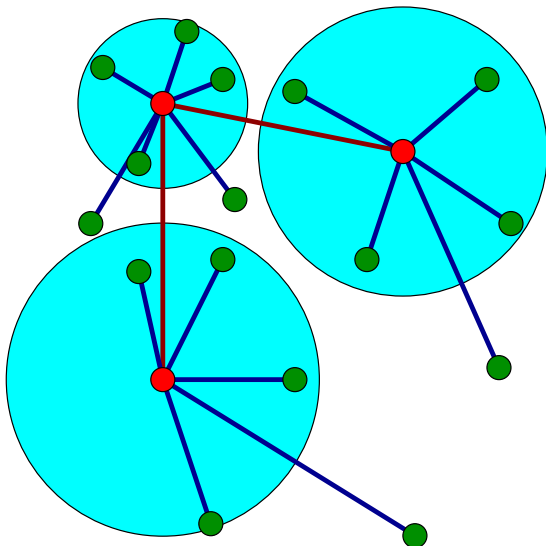


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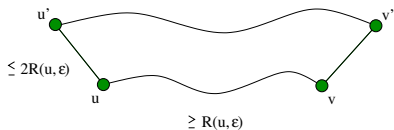




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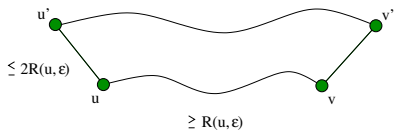


# Low Stretch



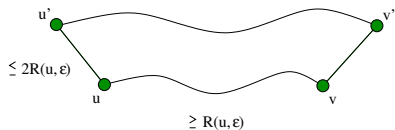
- Let  $u, v \in V$  s.t.  $v \notin N_\epsilon(u)$
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- $d(u, u') \leq 2R(u, \epsilon) \leq 2d(u, v)$
- $d(v, v') \leq d(v, u') \leq d(v, u) + d(u, u') \leq 3d(u, v)$
- $d(u', v') \leq d(u', u) + d(u, v) + d(v, v') \leq 6d(u, v)$

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- $d(v, v') \leq d(v, u') \leq d(v, u) + d(u, u') \leq 3d(u, v)$
- $d(u', v') \leq d(u', u) + d(u, v) + d(v, v') \leq 6d(u, v)$
- By spanner on  $N$ ,  $d_H(u', v') \leq t(\frac{1}{\epsilon})d(u', v') \leq 6t(\frac{1}{\epsilon})d(u, v)$
- So
 
$$d_H(u, v) \leq d(u, u') + d_H(u', v') + d(v', v) \leq (5 + 6t(\frac{1}{\epsilon}))d(u, v)$$

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## Theorem

For any metric, there is a spanner  $H$  with  $O(n)$  edges s.t. for any  $0 < \epsilon < 1$ ,  $H$  is a  $O(\log \frac{1}{\epsilon})$ -spanner with  $\epsilon$ -slack.

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Actually much simpler – only 2 layers needed:

- 1 Let  $\epsilon_0 = n^{-1/2}$ , and construct a  $\epsilon_0$ -density net  $N$  of  $V$
- 2 Connect every vertex to the closest point in  $N$
- 3 Create a 1-spanner  $H_0$  (e.g. a clique) on  $N$  (uses  $O(n)$  edges)
- 4 Use Althofer to make a  $\log n$ -spanner  $H'$  on  $V$
- 5 Set  $H$  to be the union of  $H_0$  and  $H'$ , together with edges that connect each point in  $V$  to its closest point in  $N$

# Gracefully Degrading Construction

Intuition: layers of slack spanners for various value of  $\epsilon$ .

Actually much simpler – only 2 layers needed:

- ① Let  $\epsilon_0 = n^{-1/2}$ , and construct a  $\epsilon_0$ -density net  $N$  of  $V$
- ② Connect every vertex to the closest point in  $N$
- ③ Create a 1-spanner  $H_0$  (e.g. a clique) on  $N$  (uses  $O(n)$  edges)
- ④ Use Althofer to make a  $\log n$ -spanner  $H'$  on  $V$
- ⑤ Set  $H$  to be the union of  $H_0$  and  $H'$ , together with edges that connect each point in  $V$  to its closest point in  $N$

Each step creates  $O(n)$  edges, so there are only  $O(n)$  edges total

# Stretch

Two cases for the stretch:

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- 1  $\epsilon < \epsilon_0$ : Use  $H'$  to get stretch  $O(\log n) = O(\log n^{1/2}) = O(\log \frac{1}{\epsilon_0}) = O(\log \frac{1}{\epsilon})$  between every pair of points
- 2  $\epsilon \geq \epsilon_0$ : Use  $H_0$ . Same analysis as for slack spanner, except that stretch in the net is 1, so total stretch is at most 11.

# Average Stretch

Gracefully degrading spanner automatically gives us a normal  $O(\log n)$ -spanner that has  $O(1)$  average distortion!

$$\begin{aligned} \frac{1}{\binom{n}{2}} \sum_{\{x,y\} \in \binom{V}{2}} \frac{d_H(x,y)}{d(x,y)} &= \frac{2}{n} \sum_{x \in V} \frac{1}{n-1} \sum_{y \neq x} \frac{d_H(x,y)}{d(x,y)} \\ &\leq \frac{2}{n} \sum_{x \in V} \left( \frac{1}{n^{1/2}} O(\log n) + \left(1 - \frac{1}{n^{1/2}}\right) \cdot 11 \right) \\ &= O(1) \end{aligned}$$

# Distance Oracles Overview

- Intuition: *all*-pairs shortest path is rarely necessary.
- Distance oracle: data structure/algorithm for computing approximate distances in a metric
- Want to minimize stretch, space, and query time
- First studied by Thorup and Zwick ('01): for any integer  $k \geq 1$ , oracle with stretch  $2k - 1$ , space  $O(kn^{1+1/k})$ , query time  $O(k)$
- Implicitly created a spanner, clever way of doing queries based on special structure of spanner

# Oracles with Slack

Can create slack oracles using slack embeddings:

## Theorem (ABN '06)

*For any integer  $k \geq 1$ , there is an oracle with  $\epsilon$ -slack, stretch  $6k - 1$ ,  $O(k)$  query time, and  $O(n \log n \log \frac{1}{\epsilon} + k \log n (\frac{1}{\epsilon} \log \frac{1}{\epsilon})^{1+1/k})$  space*



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But slack spanners are better:

## Theorem

*For every integer  $k \geq 1$ , there is an oracle with  $\epsilon$ -slack, stretch  $12k - 1$ ,  $O(k)$  query times, and  $O(n + k(\frac{1}{\epsilon})^{1+1/k})$  space*

Same method as used for slack spanners

# Gracefully Degrading Oracles

Can do the same thing for gracefully degrading oracles.

## Theorem

*For any integer  $k$  with  $1 \leq k \leq O(\log n)$ , there is a distance oracle with worst case stretch of  $2k - 1$  and  $O(k)$  query time that uses  $O(kn^{1+1/k})$  space such that the average distortion is  $O(1)$*

Improvement over ABN '06 if  $k = o(\log n)$

# Distance Labeling Overview

- How can we assign each point a short label so that approximate distances can be computed quickly by just comparing labels?
- Used in various networking applications
- Embedding into  $\ell_p$  very natural approach: size of a label is the dimension

# Distance Labeling Overview

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  - In general can't have dimension less than  $\Omega(\log n)$ !
  - Seems to work better in practice

# Distance Labeling Overview

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  - Seems to work better in practice
- Can we do better with spanners than with embeddings?

# Slack Labelings

Using embeddings:

Theorem (ABCDGKNS '05)

*Any embedding  $\varphi : V \rightarrow \ell_p$  with  $\epsilon$ -(uniform) slack must have dimension that depends on  $\log n$*

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*Any embedding  $\varphi : V \rightarrow \ell_p$  with  $\epsilon$ -(uniform) slack must have dimension that depends on  $\log n$*

We get rid of all dependence on  $n$  by not using an embedding!

## Theorem

*For any integer  $k$  with  $1 \leq k \leq \log \frac{1}{\epsilon}$ , we can assign each point a label that uses  $O\left(\left(\frac{1}{\epsilon}\right)^{1/k} \log^{1-1/k} \frac{1}{\epsilon}\right)$  space so that if  $v$  is  $\epsilon$ -far from  $u$ , their distance can be computed up to stretch  $12k - 1$  in  $O(k)$  time*

# Subgraph Spanner

- What if our input isn't a metric but a graph?
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- What if our input isn't a metric but a graph?
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## Theorem

*Given a weighted graph  $G = (V, E)$ , for any integer  $k > 0$  and any  $0 < \epsilon < 1$ , there exists a  $(12k - 1)$ -spanner with  $\epsilon$ -slack and  $O(n + \sqrt{n}(\frac{1}{\epsilon})^{1+1/k})$  edges.*

- Uses pairwise distance preservers of Coppersmith and Elkin to make a subgraph that emulates the spanner on the net

# Low Weight

Could also try to minimize the *weight* of the spanner.

## Theorem

*For any metric, there is an  $\epsilon$ -slack spanner with  $O(\log \frac{1}{\epsilon})$  stretch,  $O(n + \frac{1}{\epsilon})$  edges, and weight  $O(\log^2(\frac{1}{\epsilon})) \times wt(MST)$*

Main idea: use LASTs (Light Approximate Shortest-path Trees) of Khuller, Raghavachari, and Young

# Review

- Ignoring a constant fraction of distances gives us lots of power (e.g. constant stretch, linear size spanners)!
- Using  $\epsilon$ -density nets to represent metrics gives us good slack and gracefully degrading spanners, distance oracles, and distance labelings

# Future Research

- Slack version of (your favorite problem here)
- Additive spanners????

Thank You!